

18953224370



	2021-01	2022-06,2	
4		61873136	
	2020-1	2023-1	66
<hr/>			
<p>1. ; Zhijian Ji*; Lei Tian; Yuan Zhang; Distributed Multi-Robot Formation Control Based on Bipartite Consensus With Time-Varying Delays, IEEE Access, 2019, 7: 144790-144798.</p> <p>2. ; Zhijian Ji*; Haisheng Yu; Dynamic stability analysis of a tracked mobile robot based on human-robot interaction, Assembly Automation, 2019, 40(1): 143-154.</p> <p>3. ; Zhijian Ji*; Yan Yu; Hao Shi; Research on Obstacle Avoidance Method for Mobile Robot Based on Multisensor Information Fusion, Sensors and Materials, 2020, 32(4): 1159-1170.</p> <p>4. ; Zhijian Ji*; Junzhi Yu; Haisheng Yu; An angle-changeable tracked robot with human-robot interaction in unstructured environments, Assembly Automation. 2020, Vol. 40 No. 4, pp. 565-575.</p> <p>5. Zhang, P., Yue, X., Zhang, Q., ., &amp; Fang, Y.. (2021). Investigation on the influence of sic particle parameters on the machinability of sicp/al composite. Vacuum, 191(5-8), 110340.</p>			
<hr/>			